

**INTERNATIONAL CIVIL AVIATION ORGANIZATION  
ASIA AND PACIFIC OFFICE**



**GUIDANCE MATERIAL  
FOR THE ASIA/PACIFIC REGION  
FOR ADS/CPDLC/AIDC GROUND SYSTEMS  
PROCUREMENT AND IMPLEMENTATION**

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## **CHAPTER 1 INTRODUCTION**

This material has been developed under an initiative of the Regional Airspace Safety Monitoring Advisory Group (RASMAG) of the Asia Pacific Air Navigation Planning and Implementation Regional Group (APANPIRG) to assist air navigation service providers (ANSP) with the implementation of datalink-based air traffic management (ATM) systems. The material was adopted as Asia/Pacific regional guidance material by APANPIRG/18 (3-7 September 2007) under the provisions of Conclusion 18/5.

For the purposes of this document, a datalink-based ATM system is one which supports automatic dependent surveillance (ADS), controller-pilot datalink communications (CPDLC) and air traffic service (ATS) interfacility datalink communications (AIDC).

Integrated datalink systems are playing an increasingly important role in air traffic management. Datalink operations support reduced separation minima and so directly contribute to increased airspace capacity. Controller and pilot workload is reduced, and operational safety enhanced, by the automation enabled by datalink systems. As the use of these systems spreads, so more ANSPs must equip with the appropriate facilities.

The material covers two main aspects of implementation: specification and deployment.

Technical systems must be carefully specified from both the technical and operational aspects, and at the right level of detail: enough to ensure that the requirements are met, but not so much that good solutions may be excluded.

The deployment of a new system involves a number of vital steps, such as testing, training, integrating and commissioning.

This material offers guidance, rather than solutions, with the emphasis on specifying systems supporting ADS, CPDLC and AIDC. It is not the intention of this document to provide the detailed technical information required to specify datalink applications: this information may be found in the various ICAO and other documents referenced.

### **1.1 OBJECTIVE**

The objective of this document is to provide guidance on the specification, procurement and implementation of datalink systems for States and service providers unfamiliar with these systems.

### **1.2 SCOPE**

The material is divided into three sections. The first covers the generalities of procuring and implementing a new system, the second is concerned with the requirements of a datalink-based ATM system, and the third gives guidance on specifying a system.

For the purposes of this material, it is assumed that the ANSP is the organisation setting out to procure a system.

### **1.2.1 Procurement and Implementation**

Procurement and implementation includes:

- Planning and contracting
- Supervision and inspection
- Preparation for operation
- Operational transfer

### **1.2.2 Requirements**

The Requirements section covers general requirements for datalink systems and specific requirements for:

- Datalink Initiation Capability (DLIC)
- ADS
- CPDLC
- AIDC

### **1.2.3 Specification**

The Specification section offers guidance on the specification of:

- System configuration
- Interfaces
- Functionality
- Human-Machine Interface
- Capacity and parameters
- Recording and data analysis

## **1.3 SYSTEMS OVERVIEW**

A key objective of datalink systems is to support reduced separation minima: any new datalink system should be capable of supporting 30NM lateral and 30NM longitudinal separation based on RNP 4.

### **1.3.1 ADS**

Automatic Dependent Surveillance is a surveillance technique in which aircraft automatically provide, via a data link, data derived from on-board navigation and position-fixing systems, including aircraft identification, four-dimensional position, and additional data as appropriate. There are two forms of ADS:

broadcast ADS (ADS-B) and contract ADS (ADS-C). With ADS-B, aircraft broadcast positional data up to twice per second; the data may be used by ground systems (and other aircraft). With ADS-C, aircraft report directly to one or more ground systems with specified data at predetermined intervals (usually tens of minutes).

*Note: Throughout this document, the abbreviation ADS refers to ADS-C.*

The ADS data link application allows the implementation of reporting agreements, or “contracts”, which, with the exception of an aircraft in an emergency situation, are established exclusively by the ground. An ADS contract is an ADS reporting plan which establishes the conditions of ADS data reporting (i.e. the data required by the ATC system and the frequency of the ADS reports which have to be agreed upon prior to the provision of the ADS services). ADS information may be exchanged between the ground system and the aircraft by means of a single contract or a series of contracts. An ADS contract specifies under what conditions an ADS report will be initiated, and what data groups will be included in the reports.

There are three types of contract:

- *Periodic contracts* provide a report at a regular periodic interval determined by the ground system.
- *Event contracts* provide a report when or if a specified event or events take place.
- *Demand contracts* provide a single report when requested by the controller.

### **1.3.2 CPDLC**

Controller Pilot DataLink Communications (CPDLC) is a data link application that provides a means of communication between controller and pilot, using data link for ATC communications.

Sending a message by CPDLC consists of selecting the addressee, selecting and completing, if necessary, the appropriate message from a displayed menu or by other means which allow fast and efficient message selection, and executing the transmission. The messages include clearances, expected clearances, requests, reports and related ATC information. A “free-text” capability is also provided to exchange information not conforming to defined formats. Receiving the message will normally take place by display and/or printing of the message.

CPDLC overcomes a number of the shortcomings of voice communication, such as voice channel congestion, misunderstanding due to bad voice quality and/or misinterpretation, and corruption of the signal due to simultaneous transmissions.

### 1.3.3 AIDC

ATS Interfacility Datalink Communications is a data link application that provides the capability to exchange data between ATS units in support of critical ATC functions.

AIDC defines messages which are related to three phases of coordination as perceived by an ATSU.

- *Notification*, in which the aircraft trajectory and any changes may be conveyed to an ATSU from the current ATSU prior to coordination.
- *Coordination*, in which the aircraft trajectory is coordinated between two or more ATSUs when the flight approaches a common boundary.
- *Transfer*, in which communications and executive control authority is transferred from one ATSU to another.

Other AIDC messages support ancillary ATC data changes between ATSUs, including the exchange of free-text messages.

Other than the formal international communication protocol standards, internet protocol (TCP/IP) as a flexible and low cost de-fact industry standard is recommended.



## CHAPTER 2 PROCUREMENT

### 2.1 GENERAL

#### 2.1.1 System Quality

The overall quality of a system, the Total System Quality, is the product of three main elements: the quality of the design, the quality of production and the quality in operation.

The **Design Quality** is a measure how well the design process has translated the operational requirements into user specifications and the user specifications into product specifications. The design quality depends upon both the definition of operational requirements and development of user specifications by the ANSP and the system design skills of the vendor. If the operational requirements are not well defined, the specification will be compromised and the system design cannot be expected to meet the real requirements. Similarly, if the specification does not correctly reflect the operational requirements, neither will the system design.

The **Production Quality** is a measure of how exactly the products match the specifications, and applies to the hardware, the software and the integration of these to form the system as a whole. In general, the vendor is responsible for production quality.

The **Operational Quality** is a measure of how the actual operation of the system realizes the operational objectives. This depends primarily on the way the system is operated: a badly operated system is not a good system. The operational quality is mainly influenced by the operational management of the ANSP.

The **Total System Quality** is the product of design quality, production quality and operational quality. To achieve high total system quality is clearly necessary to maintain the highest possible quality in each of the three areas.

Cooperation between the ANSP and the vendor is essential to achieve a high total system quality.

#### 2.1.2 Roles and Responsibilities of the ANSP

The ANSP is ultimately responsible for successful implementation of the system. It is therefore vital that the ANSP takes a positive and active role throughout the system procurement and implementation.

The vendor is only responsible for developing and integrating a system to the ANSP's specific requirements.

Air traffic controllers, as the end-users of the system, must play a positive and active role throughout the procurement and implementation activities. The clear and complete definition of operational requirements and the final testing in an operational environment are both critical and are unlikely to be completed successfully without significant controller input. Clearly defined system requirements and specifications are vital in order for potential vendors to be able to offer a suitable system.

Controllers should also be able to contribute to the design, development and integration activities, and must be directly involved in the testing and commissioning processes.

### **2.1.3 Relationships: Requirements, Specification and Test/Evaluation**

The figure below shows the relationships between the operational requirements, the system requirements, the specification, the design and the test and evaluation process. Only the combination of a complete and feasible definition of the requirements, consistent design, quality assured development and adequate review, testing and evaluation at each stage can provide a quality system.

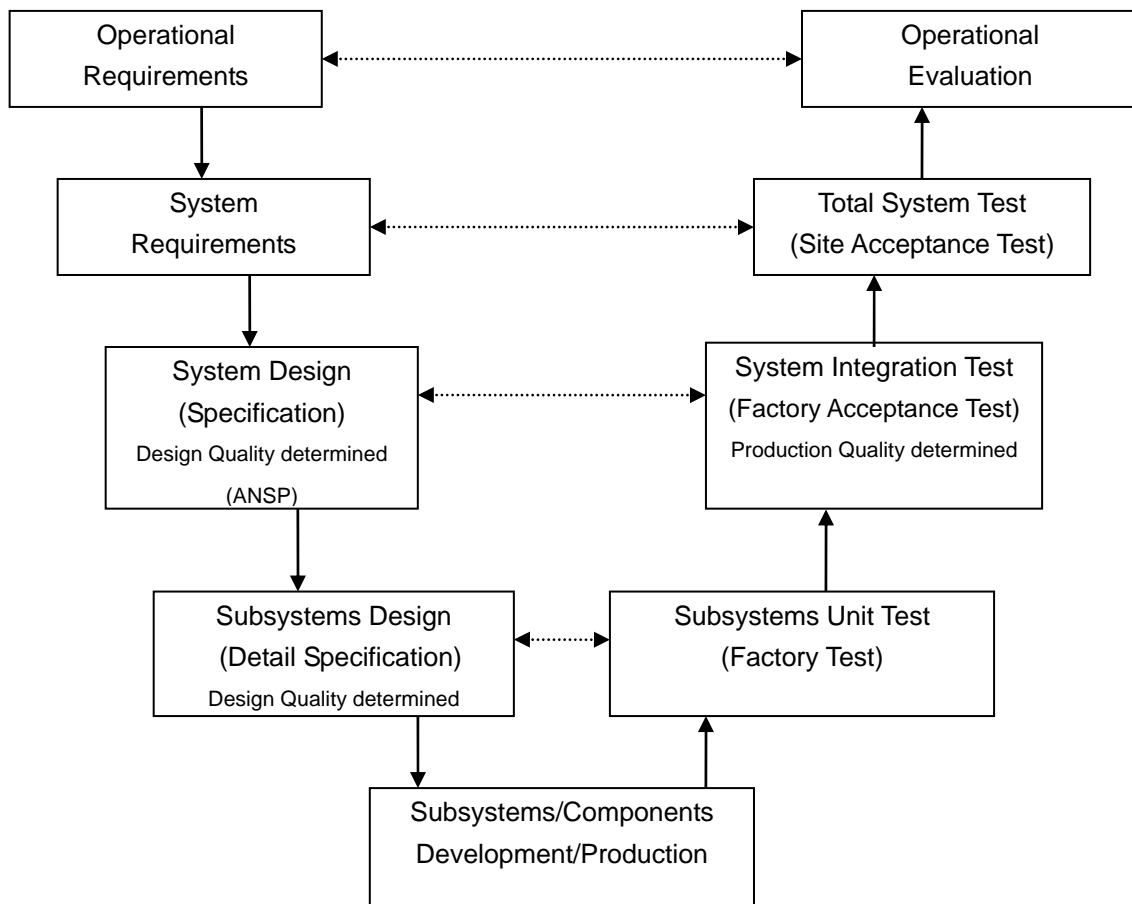


Figure1. Relationship between Requirement, Specification and Test/Evaluation

## 2.2 PROJECT MANAGEMENT

A project manager should be appointed as early as possible in the project. The basic role of the project manager is to ensure that the project proceeds within predetermined time, resource and cost boundaries. Project management requires a range of special skills, and serious consideration should be given to employing a professional project manager for the duration of the project.

The project manager must be given appropriate levels of financial and organisational authority so that he or she can make project decisions without constant recourse to higher management. It is essential that the terms of reference of the project manager are clearly documented and that they detail these authorities.

The project manager will be responsible for managing all aspects of the project, with particular emphasis on scheduling the many activities of ANSP personnel to match those of the system supplier. He or she will also play a major role in keeping the

project within the time and budget constraints by determining what, if any, changes are made to the scope of the contract.

## **2.3 PLANNING AND CONTRACTING**

### **2.3.1 Operational Requirements**

The first, and perhaps most critical, stage of the planning and contracting phase is the definition of the ATS Operational Requirements; these must clearly define precisely what the system is to do. Operational requirements should not define how the results are to be achieved – that can be done in the specification.

There is no place for choice in a requirement, and the wording must reflect this; “must”, “shall” and “will” make requirements mandatory. The use of words such as “may”, “should” and “could”, “maximum” and “minimum” and “if”, “except” and “unless” make a requirement imprecise, because the reader does not know exactly what is required. “There should be 10 sectors” or “there should be at least 10 sectors” is vague. “There will be 10 sectors” is precise and leaves no doubt as to what is required.

The operational requirements should be established by a team of experienced controllers whose professional knowledge and experience encompasses all aspects of the ATS operation; the team should also include engineers and, as necessary, other specialists.

#### **2.3.1.1 Studies of Existing Systems**

The operational requirements team must have an appreciation of how datalink systems work in the operational environment; this is best achieved by studying existing systems and talking to experienced controllers, engineers and managers in other ATS facilities. The study should cover operational and technical practices and should pay particular attention to problems encountered and lessons learnt.

Controllers using these systems will be well aware of any features that do not work well or are not user-friendly, and will have suggestions for how the system could be improved. This is valuable information that should be considered when developing the specification and during the contract negotiation phase; in the latter case, a supplier could be invited to change such features in an otherwise satisfactory system.

#### **2.3.1.2 Confirmation of Service Environments**

The operational requirements team should establish the current ATS environment as the baseline, taking into account:

- Airspace structure and major airports.

- Sector configuration and VHF/radar coverage.
- The required separation minima (30/30NM horizontal separation or better)
- Traffic flows (routes, number, flight levels, etc.).
- ATS procedures.
- Related ATS facilities.

### **2.3.1.3 Operational Requirement Analysis**

From the baseline, the team should analyse trends to determine the likely changes in the operational environment over the projected life of the system. The operational requirements can then be determined, if necessary using the projected environment at several points during the projected system life, and should detail, at the very least:

- The anticipated peak and mean traffic levels.
- The number of sectors, based on the traffic levels.
- Specific services for each sector.
- Inter-sector services.
- Inter-ATSU services.

Once these are established, the specific requirements to provide these services, such as displays and communications, can be determined.,

## **2.3.2 Design and Review**

The next stage is for the team to define the system concept in terms of both operational requirements and technical feasibility, perhaps using other facilities as a base reference. The concept should be reviewed by controllers and managers who are not part of the team; any changes proposed should be discussed with the team and the concept modified accordingly.

### **2.3.2.1 Conceptual Design**

The conceptual design must be documented clearly and should include the following:

- ATS functions needed (e.g. ADS reports, traffic display).
- Performance goals for the targeted airspace.
- Sector configuration.
- Physical configuration and layout.

- System operation (e.g. redundant parallel operation, automatic recovery, etc.).
- Standards to be applied (e.g. ARINC-745, RTCA DO-258A).
- Interface requirements for related ATS facilities.
- Datalink Service Provider (DSP) and its interface.
- Human Machine Interface (e.g. display size, use of colour, input devices).

The document should also identify any new operational procedures that may be required, both for new techniques, such as the use of ADS, CPDLC and AIDC, and for other changes.

### **2.3.2.2 Technical Feasibility Study**

The team may then determine the technical feasibility of meeting the operational requirements, particularly in terms of the functionality required, the characteristics and performance of existing systems and the available budget. Preliminary information from vendors will give an indication of the systems and capabilities that are available, so that the team can decide on the most appropriate procurement option:

- A standard “off-the-shelf” system.
- A customized off-the-shelf system.
- A custom-built system.

The criteria to be used in evaluating systems in the market will include:

- Functionality meeting the requirements.
- Adequate performance and capacity to handle future traffic.
- User-friendly and intuitive operation.
- High reliability under all anticipated service conditions.
- Simple connection with related systems and facilities.
- Required standards are met.

### **2.3.2.3 Specification**

When the operational requirements and the feasibility studies have been completed the specification can be developed. This is discussed in detail in CHAPTER 5.

#### **2.3.2.4 Design Review**

The purpose of this design review is to ensure that the conceptual design meets each and every one of the operational requirements and that it is technically achievable and attainable.

The design review team should be independent of the requirements team but should also comprise controllers, engineers and managers. The review may take the form of a walk-through of the conceptual design documents or a desk-top simulation.

The design review report should cover:

- Compliance with operational requirements.
- Connectivity with related systems and adjoining facilities.
- Flexibility and expandability in the future.
- Any operational or technical issues.

#### **2.3.3 Request for Proposal (RFP)**

A fully-documented and approved Request for Proposal (RFP) should be submitted to prospective vendors.

##### **2.3.3.1 Objective**

The objective of the RFP is to secure fully compliant proposals from a number of competent vendors.

##### **2.3.3.2 Content**

The RFP should contain all the information required for prospective vendors to make a complete and compliant proposal. Any omissions will result in enquiries from vendors, which will take time and effort to respond to. The RFP should contain:

- The specification.
- Operating environment, including:
  - External temperature and humidity ranges.
  - Temperature and humidity ranges in the equipment area and operational area.
  - Mains power supply voltage and frequency.
- Acceptance testing requirements.
- Maintenance support requirements.
- Training requirements.

- Warranty requirements.
- A draft contract, to allow vendors to see what contract requirements they will have to meet, and what arrangements they may have to make to meet them.
- Bidding conditions, including:
  - Submission of separate technical and financial bids.
  - Confidentiality.
  - The enquiry process.
  - The closing date for enquiries.
  - The closing date for bids.
  - Notification of short-listed bidders.
  - Notification of preferred bidder.
- Financial conditions, including
  - Bid bonds (if required).
  - Requirements for financing (if necessary).
  - Proposed payment schedule.
- The proposal evaluation process, including the evaluation criteria.

#### **2.3.3.3 Enquiry Process**

It is inevitable that some bidders will ask for clarification of details or for additional information. To avoid giving advantage to any particular bidder, there should be a formal process to ensure that all bidders receive the same information. This may be done by issuing a bulletin to all bidders containing each question received and the response. This should be done at frequent intervals so that vendors have time to adjust their proposals if necessary.

#### **2.3.4 Evaluation of Proposals**

Proposals must not be opened before the stated final date for bids.

The evaluation of proposals must be, and be seen to be, fair and traceable. All stages of the evaluation process should be clearly documented and the reasons for each decision recorded.

Ideally, the evaluation team will include all the members of the team that drew up the specification, complemented by other personnel as necessary. It is good practice to isolate the evaluation of the financial proposal from the rest of



the process. Besides maintaining the confidentiality of the financial bids, this avoids any influence of the technical evaluation on the financial and *vice versa*.

The evaluation process and criteria stated in the RFP must be strictly followed: this should avoid any protest by unsuccessful bidders.

Proposals are not always perfect, nor do they always fully cover every item of the RFP, and so there may be a need for clarification during the evaluation phase. It may be necessary to request additional technical or financial information in order to complete the evaluation; this should take the form of a simple request for the specific information required. However, there should be no negotiation at this stage, of either technical or financial elements.

Once the preferred bidder has been selected, the other bidders should be informed that they may be invited to negotiate if a contract cannot be concluded with the preferred bidder.

### **2.3.5 Contract Negotiation**

There should be no negotiation with bidders before the selection process has been completed. Once the preferred bidder has been determined, negotiations on the detailed conditions are acceptable. Negotiations may be by correspondence or face-to-face, and should involve the appropriate experts from the ANSP.

It is important that the negotiations cover all aspects of the contract, including the vendor's schedule. The negotiating advantage is with the purchaser until the contract is signed; it then passes to the vendor. Changes made after the contract has been signed are inevitably costly and often time-consuming.

The negotiations must be clearly documented.

If a satisfactory contract cannot be concluded, the next preferred bidder may be invited to negotiate a contract; alternatively, the tender process may be started again, but this is a costly process and is unlikely to produce a better outcome.

When the contract has been signed, the other bidders should be informed.

## **CHAPTER 3 IMPLEMENTATION**

The implementation phase begins when the contract is signed.

Typically, the vendor's activities during the implementation phase include design review, manufacture, factory testing, documentation, training, delivery, installation, site acceptance testing and handover.

The ANSP is involved in all these activities to some degree, except manufacture; but the ANSP must also prepare for the operation of the system. This will involve developing test requirements, planning training, organising staff deployment, developing procedures and planning the operational transfer from the existing to the new system.

### **3.1 IMPLEMENTATION SCHEDULE**

The project manager can now use the vendor's schedule as the basis for finalising the overall project schedule. The project schedule should detail all anticipated activities, including system design reviews, factory and site acceptance tests, training (both vendor training and internal training), commissioning and operational transfer. The schedule should also show related activities such as development of operational and technical procedures and preparation of operational material such as charts.

### **3.2 CONTRACT SUPERVISION**

The project manager is normally responsible for supervision of the contract works. This can generally be achieved by monitoring the vendor's progress reports, at least until the vendor starts work on site.

It is likely that desirable changes to the specification or the contract will be identified during design reviews or factory testing. However, careful management of change is essential. Every change will incur costs and delays.

A formal change control system should be implemented, with every change being submitted for approval only after costs and delays have been established. The procedure should identify the levels of cost and delay that the project manager can approve.

### **3.3 SYSTEM DESIGN REVIEW**

This review takes place after the vendor has completed the design for the system, and, as with the concept design review, is intended to ensure that the design meets all the operational and technical requirements. The design review is the point at which the design quality is determined. It is also the last stage at which design changes should be made; however, changes made at this stage are likely to incur costs and delays.

### **3.4 FACTORY ACCEPTANCE TEST**

The factory acceptance test is the last opportunity for the ANSP to identify problems before the system is shipped out from the factory and is the point at which the production quality is determined. It is also usually the first opportunity for ANSP personnel to examine and try out the system, and is often combined with factory-based training. It is important that operational as well as technical personnel attend the factory acceptance: it should be a test of operational features as well as of technical compliance.

The vendor should produce a detailed test schedule well before the beginning of the test, so that the ANSP can consider whether the tests meet the requirements and whether any additional tests should be included.

The results of any tests performed by the vendor before the acceptance test should be made available at the start of the acceptance test.

Any problems that are encountered during the factory test should result in agreed corrective actions to be undertaken by the vendor. These may be carried out before shipping or on site, according to the nature of the problem. The results of the factory test form an important part of the contract documentation, as they record the performance of the system and the agreed corrective actions.

### **3.5 PREPARATION FOR OPERATION**

There are a number of items that the ANSP must address in preparation for operation of the new system. These include:

- Development of operational procedures.
- Development of system management procedures.
- Preparation of system data (for maps, etc).
- Establishment of system parameters.
- Development of internal training courses for controllers, system operators and technical staff.
- Development of operational transfer plan.
- Safety assessment.

The ANSP is responsible for carrying out these tasks, although some assistance and information from the vendor will be necessary to complete them. Some of the work can be carried before the installation begins, but it may be more convenient to leave some until the vendor's specialists are on site.

While it is not appropriate for this guidance material to address each item in detail, some items do merit discussion.

### **3.5.1 Operational Procedures**

The FANS 1/A Operations Manual (FOM) has been adopted for Regional use and contains the procedures for the use of the datalink applications.

The ANSP may need to develop other procedures.

### **3.5.2 System Management Procedures**

Procedures for managing the system must be developed. These should cover such topics as system start, changeovers between “main” and “standby” systems, contingency operations, map data management, data recording and monitoring,

### **3.5.3 Preparation of System Data**

The ANSP will be required to provide data to define, for example, FIR boundaries for hand-off processing and airspace maps for the display system. The vendor will provide details of the information required and may either process the data into the system or, preferably, train and assist the ANSP staff to do so.

The preparation of this type of data can be a very detailed and time-consuming process, and due allowance should be made in the project plan.

### **3.5.4 Establishment of System Parameters**

System parameters are used to set values for a number of variables used in the software. These parameters can be changed, but normally only by software specialists. Typical system parameters include timer intervals, for example to set the default interval between ADS periodic contracts, standard range settings, display colours, etc.

The vendor will detail the system parameters and will be able to suggest suitable values; however, the ANSP must make the final decision on each parameter. The parameters should be set before site acceptance testing, so that their effect can be determined. The parameter values should be finalised before operational transfer and changes avoided during the initial period of operation.

### **3.5.5 Development of Training Courses**

It may not be practical or appropriate for the vendor to provide initial training for all personnel, and future training requirements must also be considered. The ANSP must develop its own training courses to complement the initial training by the vendor and to meet its future training requirements.

### **3.5.6 Operational Transfer Plan**

The operational transfer plan should detail each step of the transfer, particularly with regard to contingency measures to recover from system problems or unexpected operational difficulties.

For each step, the plan should give details of the timing, the people involved and any other resources that may be required. It is important to clearly define the measures or events that determine that each step has been satisfactorily completed.

It is also important that the plan is made widely available so that everyone involved understands what will happen.

The operational transfer process is discussed in 3.8 below.

### **3.5.7 Safety Assessment**

It is most important that a safety assessment (or safety case) is prepared for the introduction and operation of the system. The purpose of the safety assessment is to identify all the risks associated with the introduction and operation of the system, to establish the level of each risk and to determine how those risks can be removed or reduced to an acceptable level.

Examples of risks are ADS link failure, workstation failure, inadequate controller training, and failure to close a CPDLC message sequence.

The resulting safety assessment document will list all the risks that have been identified, the associated risk levels and the measures adopted to remove or mitigate each risk.

Safety assessments are described in detail in ICAO Doc 9859, Safety Management Manual.

## **3.6 TRAINING**

Comprehensive training is vital so that controllers, system operators and maintenance personnel must all be able to carry out their tasks competently and effectively as soon as the system becomes operational. A comprehensive training plan is a prerequisite for a successful training programme.

Training is perhaps the most important of all the preparatory tasks.

### **3.6.1 Controller Training**

While the separation standards that controllers apply will probably not change, at least not immediately on introduction of the new system, the tools they use will have changed significantly. The training must cover both the operation of the new workstations and the associated tools and, equally importantly, the procedures for using the datalink applications.

Training on the manipulation of the displays and controls should be provided initially by the vendor, and the ANSP's training staff should be included in the first courses. The training staff can then develop and deliver that training.

The procedures for the use of datalink applications have been developed within the Region and are laid out in regional documents. The vendor cannot be expected to provide training on datalink procedures; this is a task that must be performed by professional training controllers. The training modules must be developed well in advance, ideally in cooperation with the training sections of other ANSPs that have experience of datalink operations.

The timing of the training is important. There will almost certainly be several courses to train all controllers, and all training should be completed before operational transfer. The controllers on the earliest courses may have difficulty remembering what they have been taught; one solution is to provide short refresher courses shortly before operational transfer.

### **3.6.2 System Operator Training**

The operation of the system includes starting and stopping the system, switching between operational and standby units, rebooting, system recovery, changing system parameters, loading data for maps, etc, and installing software changes.

The vendor must provide the first training courses for system operators. The syllabus must include the items identified above, with sufficient background to allow the operators to understand the implications of the various actions that they will be expected to perform. They should also be given a good understanding of the various functions of the system.

The training should include practical sessions using the full system, so that the operators experience the various tasks at first hand.

### **3.6.3 Maintenance Training**

The first training courses for maintenance technicians must also be carried out by the vendor. With systems of this type, technicians must be able to diagnose faults down to circuit board level. However, as these systems include a number of computers, technicians must have an understanding of the general software structure. They should also be trained to differentiate between hardware and software faults, and to undertake simple software recovery activities.

### **3.6.4 Simulator Based Training**

If simulator facilities are provided as part of the system, a large proportion of the training can be carried out using these facilities. Simulators are particularly valuable in allowing controllers to experience unusual or

exceptional conditions, such as traffic overloads, weather deviations, route changes, emergency descents, conflicts and system failure.

### **3.7 SITE ACCEPTANCE TEST**

The site acceptance test is the last stage before handover by the vendor. This test is crucial. It is the last opportunity to identify problems while the system remains the responsibility of the vendor and should be resolved at the vendor's expense. Once the acceptance documents are signed, the vendor can fairly claim that any new problems are the responsibility of the ANSP and will seek costs if asked to rectify them.

The vendor should produce a test schedule well before the tests are due to start, but it is unlikely that the schedule will contain tests that exercise operational procedures. The ANSP, in consultation with the vendor, should develop operational scenarios that will test a wide range of procedures and functions and add these to the schedule.

#### **3.7.1 Physical Checks**

The first stage is typically a physical inspection and inventory check to ensure that all items are present and serial numbers recorded accurately. It is important to inspect the physical condition of all units and record any defects.

#### **3.7.2 Technical Tests**

This is generally followed by the technical tests which establish whether the system is correctly set up and is working properly. The system parameters are usually set during these tests, though some may need to be adjusted during the operational tests. System start-up, changeover and shut-down procedures, as well as contingency degradation and recovery processes, must also be tested.

#### **3.7.3 Operational Tests**

The operational tests determine whether the operational characteristics are correct, the controls function as expected and the system handles incoming and outgoing data correctly. There should also be tests to ensure that the system operates correctly under the specified maximum load.

These tests will typically take several days to complete as all functions must be tested from all workstations. A number of typical scenarios should be prepared in advance so that the tests can be carried out in a realistic environment.

It is essential that live testing of the datalink functions takes place. Tests of ADS and CPDLC will require the cooperation of either one or more airlines or alternatively an aircraft manufacturer with a suitable test-bench. If airlines are used, it must be quite clear that ATS instructions passed are for test purposes and are not to be complied with.

### **3.7.4 Results**

As with the factory test, it is most important to record, in detail, all problems and unusual occurrences.

The outcome of the test should include an list of corrective actions to be undertaken by the vendor within an agreed timescale.

## **3.8 OPERATIONAL TRANSFER**

The most usual ways of transferring operation to a new system are the phased transfer and the parallel operation transfer.

### **3.8.1 Parallel Operation Transfer**

The parallel operation transfer starts with old system being used operationally and the new system running in parallel with its controllers going through their tasks as though that system was operational. When the time comes to switch over to the new system, the old is system is operated in parallel for a short time as a fall-back in case of unforeseen problems. Operation of the new system need not be full-time until shortly before transfer: for example, it would be appropriate to start parallel operations during low traffic periods and work up to busy periods. H24 parallel operation is not necessary until immediately before and after transfer.

The parallel operation transfer is generally preferable as it allows the new system to be run, in its entirety, in an environment that is as close as possible to fully operational before actually taking over the operational load. However, it does require full staffing of both systems during periods of parallel operation.

### **3.8.2 Phased Transfer**

In the phased approach, operations are transferred bit by bit, typically one sector at a time, until the whole operation is running smoothly on the new system. This type of transfer may be more appropriate where the space available dictates that only one or two positions can be transferred at a time or where limited staff numbers mean that it is impossible to operate both systems simultaneously.

In this type of transfer, it is good practice to keep at least one sector available on the old system as a contingency position.

### **3.8.3 Preparation for Transfer**

The transfer must be carefully planned; in particular, there must be close coordination with external ATS units that may be affected. Staff must be thoroughly briefed before the start of the transfer process and must be kept informed of any changes to the plan.



The criteria for deciding when operations can be transferred to the new system must be clearly defined in advance. If a phased transfer is planned, transfer criteria should be set for each phase.

It is quite possible that problems will arise and it may be necessary to return the operation to the current system or to the last successful step, as appropriate. The reversion process should be established in advance – if contingencies have not been planned for, it is very likely that mistakes will be made and the problem compounded.

After the transfer has been successfully completed, it is useful to hold a debriefing to determine what went well and what did not. This can identify potential problems and possible areas of concern with both the technical and the operational aspects of the system and the new procedures.

## **CHAPTER 4 REQUIREMENTS**

### **4.1 GENERAL REQUIREMENTS**

The integrated ATS datalink system will incorporate AFN, ADS, CPDLC and AIDC.

The system will be linked with other automated systems. The FDP system provides flight plan data, such as the flight identification and flight path. The ATS operation will be enhanced if the system has the ability to feedback current aircraft positions to the FDP system to update the flight data.

The system will be linked to aircraft by a datalink service provider (DSP).

The system will be capable of transmitting and receiving AFN, ADS and CPDLC messages complying with RTCA/DO258A-EUROCAE/ED-100 and AIDC messages complying with the Asia/Pacific Regional Interface Control Document for AIDC (ICD).

The system will include the ACARS Convergence Function (ACF) to convert messages between the character-oriented data of ACARS and the bit-oriented data used in ADS and CPDLC.

The system will provide air traffic controllers with:

- Display of message exchanges.
- Display of updated aircraft positions and maps.
- Tools for measuring separation in distance or time.
- Tools for measuring angles between aircraft flight paths.
- Information on aircraft flight status.
- HMI tools for composing ADS and CPDLC messages.
- Alerts for exception conditions (e.g. expected message not received, coordination overdue).
- Conflict probe capability.
- Electronic flight progress strips, and paper strips if required.
- Presentation of emergency status.
- Other information pertinent to ATS operations.

The system capacity will be determined from:

- Traffic density at the peak hours.
- Frequency and size of messages per aircraft.

- Airspace size and number of waypoints.
- Number of FANS capable aircraft operating in the airspace.
- Anticipated growth of FANS operation.
- Number of displays.
- Number of connections for terminal systems.

#### **4.1.1 Notification of Error Messages**

The system will be capable of performing the cyclic redundancy check (CRC) on each message.

The system will be capable of format and validity checks appropriate to each message.

Controllers will be notified when the system detects:

- A message error.
- A message sequence error.
- A duplicate message identification number.
- Message non-delivery.
- An expected response not received.

#### **4.1.2 Time Stamps and Timers**

CPDLC and AIDC messages will be time-stamped; however, the form of some timestamps is actually set differently from that specified in Doc 9694.

By setting and/or deactivating various timer values for the messages received in response to transmitted messages, the system will monitor whether or not aircraft responses arrive within a specified time limit.

Timers are generally based on the operational requirements of each ATSU. However, the timers for sending messages relating to the automatic transfer of CPDLC connection and to AIDC will be set according to bilateral agreements with adjacent ATSUs concerned.

A timer file will be provided in the system for:

- Timeout settings for delayed response.
- Timing to initiate actions in ADS/CPDLC operations for:
  - Connection request (CR).
  - ADS periodic, event and demand requests.
  - Automated transfer of connection to the next ATSU.

- Sending Next Data Authority (NDA) message.
- Sending AFN Contact Advisory (FN\_CAD): at least 30 minutes prior to FIR boundary message.
- Sending End Service message prior to the aircraft crossing the FIR boundary (e.g. 5 minutes before).
- Timer to trigger actions for sending AIDC messages.
- Timer for re-transmission of the message when no response is received within a specified time.

### **4.1.3 Applicable Documents**

#### **4.1.3.1 ICAO Documents**

Annex 10, Volume III, Communication Systems

Manual of Technical Provisions for the Aeronautical  
Telecommunication Network – Doc 9750

Manual of Air Traffic Services Data Link Applications – Doc 9694

Regional Supplement to the ASTERIX Interface Control Document  
(ICD) for the Asia/Pacific Region

Asia/Pacific Regional Interface Control Document (ICD) for ATS  
Inter-facility Data Communications (AIDC), version 2

Guidance Material for End-to-End Safety and Performance Monitoring  
of ATS Datalink Systems in the Asia Pacific Region

FANS 1/A Operations Manual

#### **4.1.3.2 Industry Standards**

The industry standards for ATS datalink systems are described in the latest versions of the following documents.

- ARINC 622: ATS Datalink Applications over ACARS Air-Ground Network (end-to-end).
- RTCA DO-258/EUROCAE ED-100: Interoperability Requirements for ATS Applications Using ARINC 622 Data Communications.
- ARINC 620: Datalink Ground System Standard and Interface Specification (ground-to-ground).
- ARINC 619: ACARS Protocols for Avionics End Systems (Airborne).
- ARINC 429: Mark 33 Digital Information Transfer System (DITS).

Note: It should be noted that some message parameters for avionics are categorized as 'option' data, but provide information useful for ATS operations.

#### **4.1.4 Data Recording**

The contents and timestamps of all messages will be recorded by the system. There will be a facility to retrieve, display and printout the recorded data.

#### **4.1.5 System Performance Monitoring Tool**

The Central Reporting Agencies (CRAs) perform safety assessments of datalink performance, and to support this function, in accordance with the FOM, ATSU's are required to produce monthly statistics of end-to-end system performance in daily operations. The system performance criteria from the FOM are reproduced at APPENDIX C. The system should have appropriate tools for monitoring and analysing the performance data for reporting to the appropriate monitoring agency.

## **4.2 DATALINK INITIATION CAPABILITY**

### **4.2.1 AFN Logon Functions**

The AFN logon functions provide the necessary information to enable ADS and CPDLC communications between the system and aircraft avionics systems for:

- Logon.
- Forwarding logon information to the next ATSU.

Note: Details of Datalink Initiation Capability (DLIC) functional capabilities are provided in Doc 9694 Part 2.

The required capacity for AFN logons will be determined from the operational requirements, such as estimated number of FANS aircraft at the peak hours and anticipated growth of FANS traffic.

The system must be capable of accepting or rejecting AFN logon requests.

The system will be linked with the FDPS to correlate the AFN logon data automatically with the aircraft flight plan.

The controller's workstation should be capable of displaying the following data:

- Address and version number of the aircraft applications, if required.
- Response from the aircraft with timestamp.
- Status of correlation of the aircraft with its stored flight plan.
- Indication of 'Acceptance' or 'Rejection' to the logon request from aircraft.

When an aircraft downlinks its supported applications and their version numbers in an FN-CON message, the ground system response must indicate whether or not it supports those version numbers.

The system must be capable of sending the Acceptance message or the Rejection message with reason, as appropriate.

#### **4.2.2 Use of AIDC for Forwarding AFN Message**

The ATS system should be capable of sending the FANS application message (FAN), in accordance with the ICD. When possible, the system should use the AIDC FAN message for address forwarding in preference to the AFN application.

### **4.3 CPDLC**

#### **4.3.1 General**

The required capacity of the CPDLC function will be determined by taking account of the operational policy and procedures and the airspace characteristics, such as the number of FANS-capable aircraft, airspace size and number of waypoints, the communications necessary in ATS operations, and of the estimated future growth of datalink operations.

The system will be capable of processing the specified number of message exchanged with each of the aircraft.

Down-linked CPDLC messages will be displayed to controllers. Tools must be provided to allow simple and intuitive initiation of, or response to, CPDLC messages.

*Note: The size of the free text field is limited to 80 characters (instead of 256) for some specific aircraft types.*

CPDLC position reports should be used to display aircraft positions when no ADS report is available.

The system will have the capability of terminating CPDLC connection with the aircraft.

#### **4.3.2 Transfer of CPDLC between ATC Sectors**

The system will allow transfer of CPDLC between sectors of an ATSU without changing the data authority and with the same CPDLC link.

#### **4.3.3 CPDLC Message Exchange Requirements**

The system will be capable of handling the message set and the standardized free text messages defined in the FOM, as well as free text.

The system will allow controllers to review uplink messages prior to sending.

#### **4.3.4 Message Handling Order**

Messages will be handled in order of priority.

Messages with the same priority will be processed in the time order of receipt.

The controller will be alerted to unsuccessful receipt of the required response in the specified time or receipt of Message Assurance Failure (MAF).

#### **4.3.5 Responses**

The system will allow controllers to send any response messages linking with the reference number of the message received. The relationship between the message and its intent and the response requirement is defined in the FOM.

#### **4.3.6 Message Closure**

A CPDLC dialogue will not be closed until an appropriate closure response for that message with same reference number is received.

When the closure response message is sent, the dialogue is closed and the system will reject any further attempt to send a response message.

The capability of closing a CPDLC dialogue, independent of CPDLC closure message receipt, will be provided.

### **4.4 ADS**

#### **4.4.1 General**

The capacity of the ADS function will be determined from the operational policy and procedures and the airspace characteristics, including number of FANS capable aircraft, periodic reporting rate, airspace size, waypoint event report frequency, usage of event and demand contracts, and projected traffic growth.

The system will be capable of initiating periodic, event and demand contracts.

The system will be able to support a demand, an event and a periodic contract simultaneously with each aircraft.

The system will apply validation checks to incoming data by reference to flight plan data in relation to time, altitude, direction and position.

The system will be capable of processing ADS reports to display aircraft positions, tracks and altitude. Between ADS reports, aircraft positions will be extrapolated and displayed automatically at specified intervals.

The datalink system should have the capability of supporting 30NM lateral and 30NM longitudinal distance based separation standards.

Air and earth reference data of ADS reports will be provided for controllers if required.

The types of ADS contract are described at 5.3.1 ADS.

#### **4.4.2 Message Handling**

ADS messages will be processed by the system in the following order:

1. ADS emergency mode.
2. Demand/event reports.
3. Periodic report.

Within these categories, messages will be handled in the order received.

The following errors will be notified to controllers:

- Message validation error.
- Message sequence error detected with time stamp.
- Time-out of ADS report in response to request.
- Periodic and waypoint event report failure.

### **4.5 AIDC**

#### **4.5.1 General**

General descriptions of AIDC applications, requirements, functional capabilities, and message contents are provided in the latest version of the ICD.

The AIDC application exchanges ATC coordination information between ATSU's.

Bilateral agreements between ATSU's are necessary to determine the operational and system requirements for both ATSU's, and should be made before developing the system. These agreements should cover:

- The ICD to be applied – Asia/Pacific or other ICD.
- message set to be used.
- usage of messages (e.g. timing of transmission).

The AIDC application requires that:

- messages are generated and sent in time-ordered sequence.
- messages are delivered in the order in which they are sent.

When an ATSU queues received messages, messages with the highest urgency type will be placed at the beginning of the queue. Messages will be assigned one of the following urgency attributes:



- Normal.
- Urgent.
- Distress.

The time used in the AIDC application will be accurate to within 1 second of UTC.

A timestamp will be generated when the message is dispatched and will consist of the date (YYMMDD) and time (HHMMSS).

Where an AIDC message is linked to a previously sent message, the message will contain reference information, including the ID of the referenced message.

#### **4.5.2 Asia/Pacific Interface Control Document (ICD)**

The Asia Pacific ICD for AIDC provides the standardized procedures for inter-facility message exchanges.

(The purpose of the ICD is to ensure that inter-facility message exchanges between ATSU equipped with automated ATS systems in the Asia/Pacific Region are harmonized to a common standard.)

Until ATN becomes available, the engineering details needed to implement the exchange of messages described in Appendix A of the ICD will need to be agreed to bilaterally.

#### **4.5.3 Message Header**

Every message will contain an AFTN header. The AFTN IA-5 message header, including the use of the Optional Data Field defined in Annex 10, will be employed for the exchange of data. AFTN priority indicator FF will normally be used for all data exchanges.

A message header consists of the optional data field (ODF), addressing, message/data identification number, reference information, time stamp and cyclic redundancy check (CRC).

#### **4.5.4 ATS Coordination Messages**

AIDC provides the means by which data is exchanged between and within ATSUs for the notification of flights approaching FIR boundary, the coordination of boundary crossing conditions and the transfer of ATC services.

AIDC messages are also used to exchange emergency, track definition, and application management information as well as for transfer of surveillance data.

#### **4.5.5 Detailed Information Provided in ICD**

The appendices to the ICD describe:

- ATS coordination messages (Appendix A).
- Error codes (Appendix B).
- ATM application naming conventions (Appendix C).
- Implementation Guidance Material – IGM (Appendix D).
- Relationship to ICAO AIDC messages (Appendix E).

#### **4.5.6 Performance Requirements**

The performance requirements for the trip time of messages need to be specified and agreed to with neighbouring ATSU's to ensure effective use of AIDC. Recommended performance figures are specified in Appendix D of the ICD.

The methodology for monitoring AIDC performance is provided in Appendix A of the Guidance Material for End-to-end Safety and Performance Monitoring of ATS Datalink Systems in the Asia/Pacific Region.

## CHAPTER 5 SPECIFICATION

The development of the specification should, wherever possible, be a team effort, with operational and technical personnel working together to achieve the optimum result. System specifications should be based primarily on operational requirements; the technical specifications should be framed to support those requirements.

In developing a specification for any technical system, it is important to achieve the right level of detail. Too little detail leaves the purchaser at the mercy of potential suppliers, while too much may preclude suppliers from offering very suitable equipment. In general, it is probably appropriate to specify requirements in great detail only where those requirements are essential to the operation, and otherwise to leave the supplier a reasonable amount of freedom. An off-the-shelf system can be expected to be less expensive than one that is custom-designed.

It is also important to get the specification right. Proposals will be priced on the specification, and any changes required later, particularly after the contract is signed, will be costly in terms of price and completion time.

This section on specification covers the system configuration, its interfaces with other systems, its functionality, the operator interface, system capacity, and recording and data analysis.

### 5.1 SYSTEM CONFIGURATION

The system configuration depends upon the operational environment. In specifying the configuration, a number of issues must be considered:

- Is it to be a stand-alone ADS/CPDLC/AIDC system, is it to be part of an integrated system or is it to be interfaced with a separate ATM system?
- How many sectors are required?
- How many workstations are required per sector? If more than one, why?
- What contingency configuration is required?
- Is complete duplication of the system required?
- What are the requirements for main/standby computers and independent contingency workstations?
- Will there be duplication of communications bearers? If so, which ones?
- Assuming the normal operational configuration is one workstation per sector, how many contingency workstations are required?

## 5.2 INTERFACES

The System must have a number of interfaces to send and receive data; some of these are essential, others may be useful or just nice to have. This section concentrates on the essential and the useful.

### 5.2.1 Datalink Service Provider

In the current FANS 1/A environment, ADS and CPDLC messages are passed between aircraft and the System using the ACARS data messaging system. ACARS was developed by the DSPs to pass information between the airline operating centre (AOC) and the aircraft. ADS and CPDLC required an air-ground datalink and, in the absence of the Aeronautical Telecommunication Network (ATN), the ACARS system was used.

Access to the ACARS datalink is available only from the DSPs; ARINC and SITA are the major DSPs; they provide global coverage and complete management of the signal between the ATSU and the aircraft, including selection of most appropriate datalink path (VHF, satellite or HF). There are also some national or regional DSPs, such as AVICOM Japan.

It is essential therefore to specify the appropriate interface port(s) to connect to the chosen DSP. This is typically an RS232 serial port, but the exact requirement should be confirmed with the DSP.

### 5.2.2 ATN

It is intended that the ADS and CPDLC functions will eventually be carried by the ATN. The purpose of the ATN is to “provide data communication services and application entities in support of the delivery of air traffic services (ATS) to aircraft; the exchange of ATS information between ATS units; and other applications such as aeronautical operational control (AOC) and aeronautical administrative communication (AAC).” [Annex 10, Vol III, 3.3]

It is important, therefore, that any new system should either include provisions for, or have a defined upgrade path to provide, interfacing with the ATN.

ICAO Doc 9705 - Manual of Technical Provisions for the Aeronautical Telecommunication Network (ATN) is the appropriate source of interface data for the ATN.

At present, the ATN is under development and trials are being carried out in several ICAO Regions.

### 5.2.3 AFTN/AMHS

The AFTN is currently the carrier for ground-ground messaging between ATC units and carries AIDC messages in the FANS 1/A environment. The AHMS (Aeronautical Message Handling System) is the ground-ground messaging

application of the ATN. The AMHS is also referred to as the ATSMHS (ATS Message Handling System).

AIDC messages will be passed via the AFTN until the ATN is operational. However, AFTN/AMHS gateways will increasingly be used to provide a transition between the AFTN and ATN. These gateways transpose AFTN messages into AMHS format and vice versa.

Any new system should include at least one AFTN/AMHS gateway. AIDC messages generated in AMHS structure can then be transmitted via the AFTN and incoming messages from the AFTN will be transposed to AMHS structure. After the ATN becomes operational and the AFTN is no longer used, the gateway can be removed.

#### **5.2.4 ATS systems**

In many cases, interfaces to other ATS systems will be necessary. This may be because an ADS/CPDLC system will use the flight data or other processing capability of another system or because the new system will be directly connected to another system.

##### **5.2.4.1 Flight Data Processing System**

Where an ADS/CPDLC system is to rely on an existing system to provide flight data, the interface required will depend on the data to be passed. The ADS/CPDLC system may have no flight data processing capability and merely require flight plan information for identification purposes, or it may have some capability to up-date flight plans received from the other system and return the up-dated information.

In either case, the interface may need to transform data formats between the 2 systems. It is therefore essential that the data formats used by the existing system are detailed in the specification so that they are allowed for in proposals; otherwise, costly contract variations may be required.

##### **5.2.4.2 Radar Data Processing System**

Data imported from a separate radar data processing system will take the form of track data or possibly plot data. As with interfaces for flight data, it is most important to detail the radar data formats in the specification.

If ADS data is to be exported to a separate radar data processing system or display system, the formats required by those systems also must be detailed.

##### **5.2.4.3 Direct Connection between Systems**

When a full system (with FDPS and perhaps RDPS as well as ADS/CPDLC/AIDC) is to be connected directly to an existing system for

full data interchange, details of all the data formats of the existing system should be included in the specification.

### **5.2.5 Radar Data**

If the System is to receive direct radar feeds from existing radars, the output data format of each radar must be detailed.

Most new systems are designed around the ASTERIX surveillance data formats; specifying ASTERIX where possible will allow the greatest flexibility for the future. The ASTERIX Standard was adopted as the ICD for surveillance data exchange for the Asia/Pacific Region in 1998. Information on ASTERIX may be found at:

[http://www.eurocontrol.int/asterix/public/subsite\\_homepage/homepage.html](http://www.eurocontrol.int/asterix/public/subsite_homepage/homepage.html)

The “Regional Supplement to the ASTERIX Interface Control Document for the Asia/Pac Region” gives details of location-specific ASTERIX coding.

Inputs from military radars may be non-standard or require additional processing; any available details should be included.

### **5.2.6 ADS B Data**

Where ADS B data is available or anticipated, the system should be capable of accepting and processing such data.

### **5.2.7 Meteorological Data**

Many modern systems make provision for the use of meteorological data for updating predicted waypoint times in near-real time. However, this type of prediction may require very large amounts of data and may not be justified if experience shows that weather variations have very little effect on the routes concerned or where the weather patterns are such that occasional manual input would suffice.

If there is a requirement for regular automatic data input, the available sources of data should be investigated and the appropriate formats should be specified.

## **5.3 FUNCTIONALITY**

This section covers the core applications of the system, ADS, CPDLC and AIDC, and their supporting functions, AFN and ACF.

### **5.3.1 ADS**

ADS is a means of surveillance in which an aircraft reports its current position, intent and other pertinent information via the datalink function to an ATSU.

ADS is detailed in ARINC 745-2.

The ADS reporting rate and the types of data to report are determined by ADS contract requests from an ATSU. An aircraft can report to up to four ATSUs simultaneously.

There are three types of ADS contract: the periodic contract, the event contract and the demand (“one-shot”) contract.

#### **5.3.1.1 Periodic Contract**

The ATSU sets up a periodic contract with the aircraft to obtain regular position reports; the contract specifies to the aircraft the reporting rate, any optional data groups be added to the basic ADS report, and the frequency at which the optional groups are to be included in the reports.

Only one periodic contract can be established between an ATSU end system and a particular aircraft at any one time. The periodic contract normally remains in effect until the contract is cancelled by the ATSU.

The system must be capable of pre-defining the reporting rate as a system parameter and of allowing the controller to change the rate, on a case by case basis, to meet operational requirements.

The system must also allow the controller to include any of the permissible additional data groups in a periodic contract request.

Some systems have the capability of automatically changing the reporting rate from one area to another; however, this could increase system cost and complexity.

#### **5.3.1.2 Event Contract**

An event contract specifies a request for reports whenever a defined ‘event’ occurs. Only one event contract can be established between a ground system and a particular aircraft at any one time; however, the event contract can contain multiple event types. There are four event types.

The **Vertical Rate Change Event** is triggered when the aircraft’s vertical rate is either less than or greater than a parameter defined in the contract.

The **Lateral Deviation Change Event** is triggered when the aircraft’s actual position exceeds a lateral distance parameter from the aircraft’s expected position on the active flight plan in the FMC.

The **Altitude Range Change Event** is triggered when the aircraft’s altitude exceeds the altitude ceiling or floor defined in the contract by the ground system.

Once a vertical rate, lateral deviation or altitude range event trigger has occurred, a recurrence of this event no longer triggers an event report. If required, a new event contract must be initiated each time one of these specific events occurs.

The **Waypoint Change Event** is triggered by a change to the next or the next-plus-one waypoints. Such a change normally occurs due to routine waypoint sequencing. However, it will also be triggered by occurrences such as a change to a non-ATS waypoint entered by the pilot for operational reasons, or execution of a new route affecting the next or next-plus-one waypoints. Unlike the other event contracts, the waypoint change event trigger remains in effect for all waypoint changes.

Once an event contract has been established, it remains in effect until the specific event requests are fulfilled, or it is cancelled by the ground system.

The system must be capable of pre-defining the event trigger parameters and of allowing the controller to change the event parameters as required.

#### **5.3.1.3 Demand Contract**

The demand contract is a “one-off” request from the ground system for an ADS report containing specific data as defined in the request. A demand contract can be requested by the ground system at any time. The demand contract request does not affect any existing contracts.

The system must allow the controller to initiate a demand contract, including optional data fields.

#### **5.3.1.4 Emergency Mode**

The emergency mode can only be activated by the pilot and is normally cancelled by the pilot. While it is possible for a ground system to cancel the emergency mode status, most ground systems do not have this capability; however, some ground systems allow the controller to modify the “display” of the emergency mode status.

The system must recognise the emergency flag and display the emergency status to the controller.

### **5.3.2 CPDLC**

CPDLC provides a two-way message system between controller and pilot. It comprises an number of pre-defined up-link and down-link messages, some of which are complete in themselves, while others require data (such as time,



flight level, etc) to be added. There are also two free-text messages available in each direction, one reserved for emergency use.

To send a message, the controller selects the required message and enters any required data. (Options for selecting messages and entering data are discussed below under Human-Machine Interface.) The system then automatically codes the message in bit-oriented format and presents it for transmission.

On reception of a down-link message, the CPDLC application decodes the message and presents it to the controller.

The current message set is detailed in the FOM, and the system must provide the complete up-link message set and be capable of accepting and decoding the complete down-link message set.

Some message sequences require “closure”:

- A message requiring a response remains open until a referenced response is received.
- A message is closed when either a response is not technically required, or after a referenced response other than STANDBY or REQUEST DEFERRED has been received.

The system must manage message closure protocols in accordance with the requirements of the FOM.

### **5.3.3 ACF**

ADS and CPDLC both operate on bit-oriented data, while ACARS is character-oriented. The ACARS Convergence Function (ACF) converts the bit-oriented data of ADS and CPDLC to the character-oriented data used by ACARS, and vice versa.

If the system is to operate over ACARS, the ACF must be specified as an essential requirement.

(The ACF is not required where the ATN is the carrier.)

### **5.3.4 AFN**

The AFN function provides the transfer of information required to support the initiation of datalink connectivity between an aircraft and an ATSU. The AFN is a character-oriented application.

Because it is essential to ADS and CPDLC operation over ACARS, the AFN function as detailed in ARINC 622-4 must be a requirement of the system specification.

### **5.3.5 AIDC**

The AIDC application supports information exchanges for notification, coordination, and the transfer of communications and control functions between automated ATS systems located at different ATSU's.

The AIDC message set is defined in the ICD. This message set was based on ICAO agreed methods and messages wherever possible; elsewhere, new messages used existing ICAO field definitions to the extent possible.

## **5.4 OPERATOR INTERFACE**

### **5.4.1 Human Factors**

Human factors play a major part in the success or failure of a system to meet its operational objectives. A system that is uncomfortable to use will lead to controller dissatisfaction, which as controllers are an essential part of the overall system, can only degrade the overall system performance.

Displays and keyboards that are poorly designed from a human factors aspect will be inefficient and may cause actual harm to the users. Bad display design can affect the eyes and bad keyboard design may result in occupational overuse syndrome (repetitive strain injury). The human factors implications of the system specification should be very carefully considered, and it may be appropriate to get specialist advice.

### **5.4.2 Displays**

One or more displays are required to handle the ADS, CPDLC and AIDC messages. Many systems incorporate message handling in the situation display.

Modern displays use LCD technology and may be as large as 600 x 600mm, with typical resolution of 2048 x 2048 pixels. Smaller displays may be more appropriate for some uses, particularly if there are 2 displays at a controller position: a second display is often used for flight data handling. However, the arrangement of displays will largely depend on the extent to which the new system is to be integrated with existing systems.

While colour displays offer great advantages in differentiating between different categories of data, the choice of colours for the various categories can be very contentious. It is essential that colour allocation is not arbitrarily decided, but is based upon sound human factors principles. Inappropriate colour choices can contribute to fatigue, confusion and errors. To avoid these problems, a human factors expert should be engaged to advise on the use of colour.

Different symbols should be used for radar tracks, ADS-B tracks, ADS-C tracks and tracks generated from flight plan information. The track symbol should be that of the source of the highest quality information. At the current stage of development of ADS-B systems, radar is generally accepted as the best surveillance data, followed by ADS-B and then by ADS-C. Flight plan tracks are the lowest quality.

The status of the CPDLC connection is important information for the controller and is best displayed in the track label.

### **5.4.3 Message Handling**

Message handling for ADS, CPDLC and AIDC messages is usually achieved by some form of menu access for generating messages and by pop-up windows for replying to incoming messages. Most systems now offer access via the track label.

For CPDLC, there are two elements to generating most messages: selection of the specific message and entry of necessary data. The message selection should be simple: there are about 180 uplink messages available. Some systems present a selection of appropriate messages – for example, by offering only height-related messages if the height field in the track label is selected. ADS contract messages are more simple and infrequently required, so that a simple menu-type operation is normally adequate. AIDC messages can usually be generated automatically from flight plan data.

If a particular message handling method is required, it should be clearly stated in the specification.

The language for all menus and message sets should be English: English is the de facto language for radiotelephony within the Asia-Pacific Region. While it may seem attractive for menus and CPDLC messages to be displayed in a local language, this will inevitably lead to loss of English language proficiency and so will work against the new ICAO language proficiency provisions in Annexes 1, 6, 10 and 11. These provisions require that from March 2008, pilots, aeronautical station (radio) operators and air traffic controllers shall demonstrate the ability to speak and understand the language used for radiotelephony communications to specified levels.

### **5.4.4 Input Devices**

The controller input devices include the text input device and the pointing device.

The text input device is normally a keyboard and there are various types of keyboard (standard, ergonomic, etc). The type should be specified if it is considered important; however, it is worth noting that controllers do not have to

input large amounts of text in an ADS/CPDLC system. Touch panels may be offered instead of keyboards.

The mouse is the most common and probably most flexible pointing device; others include the track-ball and the light pen. It is difficult to locate a track-ball and keyboard so that they are well-placed for both left- and right-handed people, and light pens have been poorly received by many controllers.

Wireless connections for the input devices will reduce the clutter on the workstation working surface and allow more freedom of movement for the pointing devices. However, electro-magnetic compatibility with nearby equipment must be carefully considered.

## **5.5 CONTROLLER TOOLS**

Controller tools include such items as:

- Conflict probe
- Temporary maps
- Bearing-distance lines
- Velocity vectors
- Label overlap avoidance

### **5.5.1 Conflict Probe**

Conflict Probe is a tool to determine whether a proposed flight plan will come into conflict with another during a specified period.

The Conflict Probe is normally initiated by the controller for a particular aircraft. The probe compares the proposed trajectory with the current planned trajectories of other aircraft information and displays the position and time of calculated conflicts to the controller. The period covered by the probe is typically fairly long (up to several hours), as the main use of Conflict Probe is when a routing change is proposed under a flexible track regime.

Conflict Probe is a very complex function, requiring considerable computer power, and consequentially can be expected to be expensive.

### **5.5.2 Temporary Maps**

Temporary maps allow controllers to depict on the display areas of interest on a temporary basis. Temporary maps should be simple both to construct – a few straight lines is usually adequate – and to switch on or off on the display.

### **5.5.3 Bearing-Distance Line**

As its name suggests, a bearing-distance line allows a controller to measure the bearing and distance between 2 points on a display. The points might be an aircraft track symbol and a reporting point or 2 aircraft track symbols.

Some systems allow one or both ends of the line to lock on to an aircraft track symbol, so that the bearing and distance information displayed is updated as the aircraft move.

Multiple bearing distance lines, if available, can be useful.

### **5.5.4 Velocity Vectors**

Velocity vectors display a vector from the track symbol showing the calculated position of the track after a specific time. The time is normally preset to a default value (typically 2 minutes); most systems allow the controller to set a different value.

Some systems also allow velocity vectors to be shown for all tracks or for a selected track only.

### **5.5.5 Label Overlap Avoidance**

Label overlap avoidance allows the track labels to be moved to avoid labels overlapping one another. This is done by rotating some labels to new positions relative to the track symbol or by changing the distance of some labels from their symbols. The process is normally automatic, but should allow the controller to set selected labels to a preferred position.

## **5.6 SYSTEM CAPACITY**

The required system capacity is directly related to the number of ADS, CPDLC and AIDC messages, the number of radar tracks, the number of active flight plans, the number of workstations and so on. These, in turn, are directly related to the volume of traffic, particularly the peak traffic volume.

The system capacity is normally expressed as the number of active flight plans that the system can handle at one time; in this context, "active" means that the system is using or processing the flight plan information in some way.

It is clearly important that the system capacity should allow for traffic growth over the projected life of the system, which for modern systems is typically 5 to 7 years between major upgrades or replacement. The anticipated growth should therefore be carefully assessed using the best projections available, and should allow for daily and seasonal traffic peaks.

However, it is also important not to set the capacity requirement too high, as this will almost certainly result in increased cost.

Some growth rates over those periods are shown below to give an indication of future capacity requirements based on current traffic:

Anticipated Annual Growth	Total Growth over		
	5 years	6 years	7 years
5%	28%	34%	41%
7.5%	44%	54%	66%
10%	61%	77%	95%

## 5.7 RECORDING AND DATA ANALYSIS

The system should record all incoming and outgoing ADS, CPDLC and AIDC messages for use in incident and accident investigations. It is imperative that all recordings are time-stamped. Messages are typically recorded onto a tape cartridge or DVD, and the system should allow change-over of the cartridge or DVD with no interruption to the recording.

Annex 10 Vol II and Annex 11 require communications, including AIDC and CPDLC, to be recorded and the recordings to be retained for at least 30 days for accident/incident investigation purposes. Chapter 3 of the FOM details some specific recording requirements for both safety investigation and performance monitoring.

The recording system should allow replaying of the situation and identification of messages were sent or received by the system.

Provision should also be made for recording data for use by the agencies monitoring RNP, RVSM and datalink performance. These are the Safety Monitoring Agency (SMA), the Regional Monitoring Agency (RMA) and the Central Reporting Agency (CRA) respectively. Generally, the data required by RMAs and SMAs is captured by the FDPS.

To meet CRA requirements, the specification should include a requirement for datalink performance monitoring tools and analysis software. The analysis software should, at the least, be capable of extracting time-stamps, addressees and message types from all incoming and outgoing messages.

The table below summarises the FOM datalink monitoring requirements for ANSPs.

<b>Requirements</b>	<b>Monitor/Record</b>
Operational Procedures	Time stamped ATS messages with identification and reference numbers
	Message Assurance
	Anomaly event report
Performance	End-system availability
	Transit times
Safety (i.e. operational, performance and interoperability requirements which are used to mitigate the effect of a failure condition)	Time stamped ATS messages with identification and reference numbers/MAS
	Anomaly event reports
Interoperability	Time stamped ATS messages with identification and reference numbers/MAS

## APPENDIX A GLOSSARY

ACARS	Aircraft Communications Addressing and Reporting System
ACAS	Aircraft Collision Avoidance System (ICAO)
ADS	Automatic Dependent Surveillance
AEEC	Airline Electronic Engineering Committee
AFN	ATS Facilities Notification
AFTN	Aeronautical Fixed Telecommunication Network
AIDC	ATC Inter-Facility Data Communications
AIP	Aeronautical Information Publication
AMHS	Aeronautical Message Handling System
ANSP	Air Navigation Service Provider
AOC	Airline Operational Communications
APANPIRG	Asia/Pacific Air Navigation Planning and Implementation Regional Group
ARINC	Aeronautical Radio Incorporated
ATC	Air Traffic Control
ATM	Air Traffic Management
ATN	Aeronautical Telecommunication Network
ATS	Air Traffic Services
ATSMHS	ATS Message Handling System
ATSU	ATS unit
AVICOM	AVICOM Japan Co. LTD
CAA	Civil Aviation Authority
CNS	Communications, Navigation, Surveillance
CPDLC	Controller Pilot Data Link Communications
CRA	Central Reporting Agency (for datalink)
CRC	Cyclic Redundancy Check
DL	Downlink message
DSP	Datalink Service Provider
EUROCAE	European Organization for Civil Aviation Equipment
FANS	Future Air Navigation System
FIR	Flight Information Region
FIT	FANS Interoperability Team (IPACG, ISPACG) FANS Implementation Team (FIT-BOB, FIT-SEA)
FMC	Flight Management Computer
FMS	Flight Management System
GES	Ground Earth Station (satellite)
GPS	Global Positioning System (USA)
HF	High Frequency (3-30 MHz)
IATA	International Air Transport Association
ICAO	International Civil Aviation Organisation



IFATCA	International Federation of Air Traffic Controllers Associations
IFALPA	International Federation of Air Line Pilots' Associations
IPACG	Informal Pacific ATC Coordinating Group
ISPACG	Informal South Pacific ATS Coordinating Group
MAS	Message Assurance (data message)
MCDU	Multipurpose Control Display Unit (ACARS & FMC)
MU	Management Unit (ACARS)
NDA	Next Data Authority
NOTAM	Notice To AirMen
RASMAG	Regional Airspace Safety Monitoring Advisory Group
RMA	Regional Monitoring Agency (for RVSM)
RNP	Required Navigation Performance
RTCA	RTCA Inc.
RVSM	Reduced Vertical Separation Minima
SATCOM	Satellite Communication
SATVOICE	Satellite Voice Communication
SITA	Société Internationale de Télécommunications Aéronautiques
SMA	Safety Monitoring Agency (for RNP)
SR&O	System Requirements and Objectives (FANS-1 document)
TCAS	Traffic Alert and Collision Avoidance System (USA)
TMU	Traffic Management Unit
UL	Uplink message
VHF	Very High Frequency (30-300 MHz)

## APPENDIX B REFERENCES

Annex 10, Volume III, Communication Systems		ICAO
Procedures for Air Navigation Services, Air Traffic Management	Doc 4444	ICAO
Manual of Technical Provisions for the Aeronautical Telecommunication Network (ATN)	Doc 9750	ICAO
Basic Air Navigation Plan – Asia and Pacific Regions	Doc 9673	ICAO
Manual on Airspace Planning Methodology for the Determination of Separation Minima	Doc 9689	ICAO
Manual of Air Traffic Services Data Link Applications	Doc 9694	ICAO
Safety Management Manual	Doc 9859	ICAO
Asia/Pacific Regional Plan for the new CNS/ATM Systems		ICAO Asia Pacific Office
Regional Supplement to the ASTERIX Interface Control Document (ICD) for the Asia/Pac Region		ICAO Asia Pacific Office
Asia/Pacific Regional Interface Control Document (ICD) for ATS Inter-facility Data Communications (AIDC), version 2		ICAO Asia Pacific Office
Guidance Material for End-to-End Safety and Performance Monitoring of ATS Datalink Systems in the Asia Pacific Region		ICAO Asia Pacific Office
FANS 1/A Operations Manual		
Interoperability Requirements for ATS Applications using ARINC 622 Data Communications	DO-258A / ED-100A	RTCA and EUROCAE
Air-Ground Character-Oriented Protocol Specification	618-5	ARINC
Data Link Ground Systems Standard and Interface Specification (DGSS/IS)	620-5	ARINC
ATS Data Link Applications Over ACARS Air-Ground Network	622-4	ARINC
Aircraft Communications Addressing Reporting System (ACARS)	724B-5	ARINC
Air Traffic Services Systems Requirements & Objectives (ATS SR&O)		Boeing

## APPENDIX C PERFORMANCE CRITERIA

Criteria	Definition	Values
<b>Performance</b>	End-to-end round trip time for uplinks. (from sending of the uplink until reception of the MAS)	Round trip time of 2 minutes, 95% of messages. Round trip time of 6 minutes, 99% of messages.
	End-to-end one way time for downlinks. (comparison of message time stamp and receipt time)	One way time of 1 minute, 95% of messages. One way time of 3 minutes, 99% of messages
	Uplink messages only: Undelivered messages will be determined by: <ul style="list-style-type: none"> <li>• Message assurance failure is received. After trying both VHF and SATCOM. Depending on reason code received, the message might, in fact, have reached the aircraft.</li> <li>• No message assurance or flight crew response is received by ATSU after 900 seconds</li> </ul>	Less than 1% of all attempted messages undelivered
<b>Availability</b>	The ability of the network data link service to perform a required function under given conditions at a given time:	99.9%
	The maximum allowed time of continuous unavailability or downtime should be declared (MTTR)*	TBD
<b>Reliability</b>	The ability of a data link application/system to perform a required function under given conditions for a given time interval: it can be expressed in MTBF (Mean Time Between Failure) *	TBD
<b>Integrity</b>	The probability of an undetected failure, event or occurrence within a given time interval.	$10^{-6}$ /hour

\* Availability =  $MTBF \times 100 / (MTBF + MTTR)$

*Note: RTCA SC189/EUROCAE WG 53 defines the performance requirements for specific operational environments.*